A wide range of hardware combination always equipped with all the special software functions make these instruments highly flexibles.

The use of a custom display able to get at a glance the complete process status together with internal and external software solutions make an easy configuration and assure an excellent operator interface.

General features

- The configuration software allows to simplify the instrument configuration, the run time parameter setting and the program construction.
- SDDE driver is a simple object oriented interface between ERO instruments and Windows[®] applications.
 Windows[®] is a Microsoft Corporation registred trademark
- Three rows 4-digit LED display for an excellent operator interface.
- 2 bar-graph LED display (MKP and MKC).
- IP 65 and NEMA 4X front protection.
- Programmable digital filter on the measured value and on the retransmitted value.
- Open input circuit alarm.
- Control output security value.

Controllers (MKC - PKC)

- 4 digital outputs.
- 2 isolated mA outputs.
- Remote set point input + trim function.
- UL and cUL approved.

Programmers (MKP - PKP)

- Clock calendar function for the automatic start, daily or weekly, of a selectable program.
- 200 segments available.
- Up to 90 programs, each program can be composed by a different number of segments.
- Up to 9 linked programs (each one can encompass up to 9 independent programs).
- 5 PID parameters groups and 10 wait bands.
- Up to 14 break events are programmable for each segment.
- Up to 14 timer events selectable for each program.
- Up to 11 logic inputs and 14 digital outputs (relay, SSR, or servo).
- 2 isolated mA outputs.
- Output Power Off function.









FRONT EXTRACTION

The design of some innovative mechanical solutions allows to make the instrument extraction particularly easy. In fact, it does not require any tool and the extraction force is very little whereas the front lock assures a safe and vibration resistant fixing.

CONFIGURATION



Configuration program

The configuration package is a special software developed to simplify instrument configuration, run time parameters setting and program construction. The capability to memorize a complete configuration set, offers a quick and reliable configuration system and deletes maintenance time loss. The capability to print a configuration report increases work traceability (as required by the Quality Systems) and simplifies plant analysis.

> HOW TO ORDER configurator: 6ER.CNF.000.XXX

SDDE

DDE communication driver for ERO electronic devices

How can you simply create a dinamic link between ERO instruments and a PC running Windows®? Now it is quick and inexpensive by using SDDE driver developed by ERO Electronic to make available, as Windows objects, the process data handled by the instruments as well as there run-time and configuration parameters. The integration of ERO instruments in the Windows work environment allows to link them to any Windows

based package like Excel, Word, etc., and simplifies the building up of your own application by using any other tool like In-Touch, Visual Basic and similar.

Windows® is a Microsoft Corporation trademark







Split range of the output

This function allows you to drive two different physical outputs (two different actuators) with the same calculated output. The possibility to set different bias and gain for the two phisical outputs gives: - better control accuracy [ex. for a

- better control accuracy [ex. for a better flow control it is possible to use two small valves instead of a big one and set the
- instrument as in drawing (1)] energy saving possibilities (ex. for air ventilation it is advisable to drive only a part of the available fan and to drive the remaining one when the first part reaches the 100 % of its capability)

 a 3-segment output characteristics as shown by the drawing (2) [Special process]







Square root extraction on the measured value.

These instruments offer the possibility to extract the square root of the measured value. This function allows to measure a flow with a standard DP transmitter and without any other apparatus.

Auxiliary power supply.

These instruments can be equipped with a non isolated auxiliary power supply able to simplify the connection with a 2, 3 or 4-wire transmitter.



Preprogrammed output characteristics

This instrument allows to the user to select an output linearization in accordance with the two most common valve flow characteristics: - Quick opening

- Equal percentage.

This function allows to linearize the ratio between flow rate and valve travel in order to obtain a better control of the process.

Alarm on the output values

This function allows to set alarm thresholds directly on the control output percentage of the instrument. This possibility simplifies the control of these process where it is necessary to generate an action related only with the control output percentage.

Example: the instrument is controling a process by driving an air flow valve. The air flow generator is composed of 3 fans; the first one is always ON while the second and third are turned ON when the power output reaches the programmed value [33 % (AL 1) and 66% (AL 2)]. This solution allows to reduce power consumption and improve control quality.

Power output





GENERAL SPECIFICATIONS

	Case:	Polycarbonate			
	Self extinguishing degree: Front protection:	 According to UL 746 C. designed and tested for IP 65 and NEMA 4X for indoor locations (when panel gasket is installed). Test performed in accordance with IEC 529, CEI 70-1 and NEMA 250-1991 ST 			
	Installation: Rear terminal board:	 panel mounting 32 screw terminals for MKC, PKC and PKP (54 for MKP) with 			
	Dimensions: (according to DIN 43700)	48 x 96 mm for 96 x 96 mm for	Igram and safety rear cover PKP and PKC MKP and MKC		
	Weight:	500 g for PKP a 600 g for MKC 700 g for MKP.	nd PKC		
	Power supply: (switching type)	from 100 to 240 or 24 V DC/AC	V AC 50/60 Hz (from +10 % to (<u>+</u> 10% of the nominal value).	9-15% of the nominal value)	
	Power consumption:	15 VA max. for 16 VA max. for 20 VA max. for	PKC MKC and PKP MKP		
	Insulation:	a double or rein supply and all the	forced insulation is guarante the instrument inputs and out	ed between the power	
	Common mode rejection ratio:	> 120 dB @ 50/	60 Hz.		
	Normal mode rejection ratio:	> 60 dB @ 50/6	0 Hz.		
	Electromagnetic compatibility and safety requirements:	This instrument directives 89/33 and EN 50082-2 (reference harm	is marked CE. Therefore, it 6/EEC (reference harmonize 2) and to council directives 7 onized standard EN 61010-	is conforming to council ed standard EN 50081-2 3/23/EEC and 93/68/EEC 1).	
	Resolution:	30000 counts.		,	
	Sampling time:	125 ms for linea	r inputs or RTD		
	Accuracy:	± 0.2% f.s.v., @	25 °C and nominal power s	upply	
	Operating temperature: Storage temperature:	from 0 to +50 °C	°C		
	Humidity:	from 20% to 859	% RH not condensing.		
MEASURING INPUT	All inputs are factory calibrated and It si possible to apply a first order d programmed within 0 and 8 second	d selectable by fro ligital filter on the o ds.	ont keyboard. displayed value. The time co	nstant of the filter may be	
K i D input	Calibration: Line resistance: Burn out:	according to DII Max. 20 Ω/wire Detection of the circuit. The instr	vonnection N 43760 with no measurable error. sensor open circuit and of c ument shows the short circu	one or more wires open it indication when the	
	Standard ranges:	from -200 to 850 from -330 to 156	20 °C or from -199.9 to 850.0 50 °F or from -199.9 to 999.9	°C) °F.	
Thermocouples	Line resistance compensation error: Burn out:	max.±0.1%ofinp Detection of the overrange selec	outspan with input impedance≤1 open input circuit (wire or s table indication.	l00Ω. ensor) with underrange or	
	Cold junction:	automatic compe	ensation for an ambient temper	ature between 0 and 50°C.	
	Input impedance: Calibration:	> 1M Ω . according to IE0	C 584-1.		
	STANDARD RANGES TABLE	TC type	°C	Range °F	
		B	0 / 1820	+32 / 3300	
		С	0 / 2300	0 / 4170	
		D	0 / 2300	0 / 4170	
		E	-100 / 800	-150 / 1470	
		G	0 / 2300	0 / 4170	
		L	-100 / 900	-150 / 1650	
		J	-100 / 1000	-150 / 1830	
		N	-100 / 1370	-150 / 2550	
		Ni/NiMo	0 / 1100	0 / 2000	
		R	-50 / 1760	-60 / 3200	
		S	-50 / 1760	-60 / 3200	
		Т	-200 / 400	-330 / 750	
		U	-200 / 600	-330 / 1110	

Linear inputs (mA and V)	Input linearization: Readout: Decimal figure:	programmable squa keyboard programm programmable in an	re root extractio able from -1999 y position.	n. to 9999.	
	STANDARD RANGES TABLE	Inp	ut	Imped	ance
		0 - 20	mA	5	Ω
		4 - 20	mA	5	Ω
		0 - 60	mV	> 1	MΩ
		12 - 60	mV	> 1	MΩ
		0 - 5	V	> 200	kΩ
		1 - 5	V	> 200	kΩ
		0 - 10	V	> 400	kΩ
		2 - 10	V	> 400	kΩ
Auxiliary input (optional) Function: for MKP algebrai for MKC or as rei Type: not isola Scaling: program position Sampling time: 500 ms. Accuracy: ± 0.2% ± 1digit Temperature drift: 300 ppr		for MKP - PKP this input can be used as trim function, algebraically added between this value and the operative set point. for MKC - PKC this input can be used as trim function, or as remote set point input. not isolated programmable from -1999 to 9999, the decimal figure is automatically positioned as for main input. 500 ms. ± 0.2% f.s.v. ± 1digit @ 25 °C and nominal power supply voltage. 300 ppm/°C.			
	STANDARD RANGES TABLE	Inp	ut	Imped	ance
		0 - 20	mA	5	Ω
		4 - 20	mA	5	Ω
		0 - 5	V	> 200	kΩ
		1 - 5	V	> 200	kΩ
		0 - 10	V	> 400	kΩ
		2 - 10	V	> 400	kΩ
OUTPUTS	Types:	these products may (relè, SSR, TRIAC c outputs (mA).	be supplied with or servomotor dri	up to 4 digital over and up to 2	outputs linear
Digital outputs					
OUT 1 and 2	Function: Type:	singularly programm - control output - alarm output - event output. relay, SSR or TRIA0	ned as: C.		
OUT 1 and 2 - Relay	Relay type: Contact rating:	SPDT 3 A @ 250 V A.C. or	n resistive load.		
OUT 1 and 2 - SSR	Туре:	not isolated voltage - Logic level 1: 14 V - Logic level 0: < 0.5	outputs. @ 20 mA max. : V c.c.	24 V @ 1 mA.	
OUT 1 and 2 - TRIAC	Switching mode: Triac rating:	isolated zero crossin from 50 mA to 1 A from 24 V _{ms} to 250 \	ng type. / _{ms}		
OUT 3 and 4	Function: Type: Contact rating:	singularly programm - control output - alarm output - event output. - Servomotor drive (relay SPST. 3 A @ 250 V A.C. o connected together	od as: OUT 3 open, O n resistive load. with the same re	UT 4 close). The OUT 3 and ear terminal.	4 commons are
Servomotor output	Type: Servomotor output type: Feedback potentiometer input: Servomotor travel time: Servomotor dead band:	Type:two relays interlocked (OUT 3 and 4).type:- Close loop - Open loop with valve position indication only. - Open loop without valve position indication.input:from 100 Ω to 10 k Ω .I time:from 12 seconds to 3 minutes. from 1% to 50% of the feedback span or of the valve travel tim		e travel time.	



Analogoutputs		
OUT 5 and 6	Function:	programmable as - Control output - Analog retransmission of the measured value - Analog retransmission of the operative set point
	Output type:	Isolated output programmable as: 0-20 mA 4-20 mA.
	Scaling: Maximum load:	programmable from -1999 to 9999. 600 Ω .
	Accuracy:	0.1% when it is used as control output.
	Filter:	it is possibleto apply a first order digital filter on the retransmitted value. The time constant of the filter may be programmed within 0 and 8 seconds.
CONTROL ACTION	Algorithm:	PID + SMART
	Types:	 one control output (digital or analog output) one control output splitted on two outputs (split range). two control outputs.
		The outputs can be freely selected among
	Disital systems tomas	analog, digital or servo.
	Digital output types:	relay, SSR of TRIAC.
	Analog output types:	linear (20 mA).
	Servomotor output:	Two relays interlocked.
Ukreteree	Proportional band:	programmable from 0.5% to 999.0% of the input span. Setting a PB equal to 0 the control action becomes ON/OFF.
nysteres	Integral time:	programmable from 1 second to 20 minutes or excluded
	Derivative time:	programmable from 1 second to 10 minutes or excluded.
	Integral preload:	programmable
		 for one control output, from 0 to 100% of the output range. for two control outputs, from -100% to +100% of the heating/cooling output range.
	Main output cycle time: Secondary output cycle time:	from 1 second to 200 seconds. from 1 second to 200 seconds
R	elative secondary output gain: Overlap/dead band:	programmable from 0.20 to 2.00 referred to proportional band. programmable from -20% (dead band) to +50% (overlap) of the proportional band.
	Output limiters:	or main and/or secondary control outputs it is possible to set: - output high limits - output low limits
		- output max. rate of rise.
	AUTO/MANUAL mode:	selectable by front pushbutton or logic input.
ALARMS	Alarm action:	Direct or reverse function programmable.
		deviation alarm or process alarm on the output value.
	Alarm reset:	Automatic or manual reset programmable for each alarm.
	Alarm masking:	each alarm can be configured as masked alarm or standard alarm. This function allows to delete not desired alarm indications at instrument start up and after a set point changement.
Process alarm	Operative mode:	minimum or maximum programmable.
	Threshold:	programmable in engineering units within input range.
	Hysteresis:	programmable in engineering units from 1 to 200 digits.
Band alarm	Operative mode: Threshold:	inside or outside programmable. two thresholds are programmable: low - from 0 to -1000 units.
	Hysteresis:	nign - trom 0 to +1000 units. programmable in engineering units from 1 to 200 digits.
Deviation alarm	Operative mode:	high or low programmable.
	Sodia:	programmable from -1000 to +1000 units.
	Hysteresis:	programmable in engineering units from 1 to 200 digits.

Alarm on the main output values	It is possible to obtain an alarm condition when the main control output is lower or higher than a programmed value.				
	Operative mode: threshold: Hysteresis:	minimum or maximum programmable. programmable from 0.1 to 100.0% of the output. programmable in engineering units from 0.1 to 20.0% of the output.			
Alarm on the secondary output values	It is possible to obtain an alarm con programmed value.	is possible to obtain an alarm condition when the secondary control output is lower or higher than a rogrammed value.			
	Operative mode: threshold: Hysteresis:	minimum or maximum programmable. programmable from 0.1 to 100.0% of the output. programmable in engineering units from 0.1 to 20.0% of the output.			
Output failure detection (OFD function) (optional)	put failure detection Dfunction) onal) The instruments equipped with this feature are capable to measuring, by means of a CT, current of one control output. During the ON period of the output, the instrument measures the current through the loa an alarm condition when this current is lower than a pre-programmed threshold value (a a partial or total break down of the load or of the actuator). During the OFF period of the output, the instrument measures the leakage current throug generates an alarm condition when this current is higher than a pre-programmed threshold value (a current is higher than a pre-programmed threshold value)				
	Input range: Scaling: Resolution: Active period:	50 mA AC. programmable from 10 A to 100 A (with 1A step). - For full scale up to 20A : 0,1A - For full scale from 21 A to 100 A: 1A - For relay output: NO or NC programmable. - For SSR output: logic level 1 or 0.			
	Minimum active period to perform the measurement:	120 ms. This function is applicable only to a control output programmed as proportional time output (relay or SSR)			
Serial interface (optional)	Type: Protocol type: Baud rate: Byte format: Parity: Stop bit: Address: Output voltage levels:	RS 485 isolated. MODBUS, JBUS. programmable from 600 to 19200 BAUD. 8 bit. even, odd or none programmable. one. from 1 to 255. According to EIA standard.			
Auxiliary power supply (Optional)	Type: Max. current:	24 V DC ± 20% not isolated. 25 mA.			





MKP and PKP programmers

PROGRAMMER

Program flexibility

These instruments allow to create programs with different number of segments. For example, 4 programs are created.

The program N° 1 is composed by 9 segments.



The program N° 8 is composed by 15 segments.



The program N° 22 is composed by 4 segments.



The program N° 45 is composed by 67 segments.



The 105 remaining segments (95 of 200 are used) can be used to create new programs or to modify the already existing one's.

Linked programs

Right side is shown a linked program (L1). It is formed of 3 sigle programs (7, 20, e, 5)

(7, 20 e 5). If a difference between the final set point of a program (A) and the initial set point of the next program (B) occurs; the wait function will guarantee the correct execution of the first segment of the next program. (C).





Timer events

This function allows to associate to a program one or more outputs selected as timer event (ex. OUT 19). These timers are synchronized to the program starting and each

one of them is composed of 5 steps maximum and they are independent of the program profile. Each step is associated to an

Each step is associated to an output state, as shown in the example, and it is programmable from 1 second to 99 hours and 59 minutes.

Break events

With this function it is possible to associate to each segment the state ON or OFF of one or more outputs selected as break event (ex. OUT 10).

MKP and PKP programmers

PROGRAMMERS SPECIFICATIONS

SEGMENTS	Up to 200 segments are available. For each segment is possible to: - set its duration in hours and minutes (up to 99 h and 59 m) or in minutes and seconds (up to 99 m and 59 s); - relate to a group of PID parameters chosen among 5; - relate to a wait band chosen among 10; - relate to one or more break event.			
SIMPLE PROGRAMS	Up to 90 simple programs are available. For each simple program it is possible to: - use a different number of segments up to 99; - set the program repetitions; - set the instrument behaviour after the last programmed cycle is carried out; - relate to up to 14 timer events; - relate to an end of cycle indication; - relate to an end of profile indication;			
LINKED PROGRAMS	Up to 9 linked programs are available. - each linked program can include up to 9 simple programs.			
FUNCTIONS AVAILABL	E EDI ¹	The Edit mode allows to create, to modify or to delete programs.		
when a program is in progr	'ess Wait	This function keep automatically frozen the progress of the operating program if the process value is outside the wait band. The progress of the program will automatically restart when the process value will return inside the wait band.		
	HOLD	 By this function it is possible to temporarily stop the operating program. 		
	ABORT	by this function the operating program is aborted, the instrument reverts to Edit mode.		
FAST		This function allows to reach, 60 times faster than the normal speed, a particular point of the profile, forward or backward, from where it is desired to restart the program.		
	JUMP By this function it is possible to jump from the operating segment to the beginning of the next or the previous segments.			
PROGRAM	This function allows to select by inputs.	an external device (ex. PLC) the operating program acting through logic		

INPUTS

Each logic input used for the program selection is related to a weight of binary code. In the example below, the logic inputs Dig 2, In 1 and In 4 are used for program selection.

Programs	Input	Weight	Input	Weight	Input	Weight
rigianio	Dig 2	2º	In 1	2 ¹	In 4	2 ²
1	On		Off		Off	
2	Off		On		Off	
3	On		On		Off	
4	Off		Off		C	Dn
5	On		Off		On	
6	Off		On		On	
7	On		On		On	
					•	

END OF CYCLE AND END OF PROFILE FUNCTIONS



This example shows a program formed by 4 segments and it is repeated for 3 times.

END OF CYCLE

This function allows to automatically get an indication, by a digital output, whenever a program cycle is ended. The status (ON or OFF) of the output and its duration can be programmed.

END OF PROFILE

This function allows to automatically get an indication, by a digital output, whenever a profile is ended. The status (ON or OFF) of the output and its duration can be programmed.



SPECIAL FUNCTIONS	
Clock calendar (Optional)	By this function, the operator presence is not required to start the operating program. For the automatic starting it is possible to set: 1) the day of the week selected among: - one day only (monday, tuesday, etc) - daily - daily - daily without sunday - daily without saturday and sunday 2) the starting time 3) the operating program. A lithium battery assures to the internal clock the correct working (even when the instrument power supply is OFF) for more than 10 years.
Output Power OFF	This operative mode simplifies the process management where zone switches or any other device to disable the process control are used. This function disables the control outputs, the retransmissions, the alarms and the control algorithm at the same time. In this mode, the instrument operates as an indicator and the process variable can be checked out even if the system is OFF or the zone is disabled. When power up is resumed, the instrument sets to zero the integral action of the control signal and enables the soft start and alarm masking functions. This function is particularly advantageous used in combination with the clock calendar function. For example, by using a relay as output power OFF annunciator, it is possible to turn OFF the system (manually or automatically) and turn it ON automatically when the time programmed by clock calendar function is reached. When the system is turned ON, the instrument starts the execution of the selected program and also activates all functions used at start up (soft start and alarm masking).
Additional outputs (optional)	For the MKP only, 5 + 5 digital outputs are available. Function: singularly programmable as event output Type: Relay type SPST. Contact rating: 0.5 A @ 250 V AC on resistive load. Note: The C side of all relays is connected in common.
Events	All the digital outputs can be programmed as events. It is possible to set an event choosing among the following types: - Break event - Timer event - End of cycle annunciator - End of profile annunciator - Program run annunciator - Program wait annunciator - Output Power OFF mode annunciator - Error condition on the main input (overrange, underrange, open or short circuit). - Error condition on both measuring inputs. - Auto/Manual mode annunciator.
Logic inputs	Function: these instruments are supplied with 3 standard logic inputs, programmable as: - auto/manual selection - output limiter activation - output limiter activation - manual reset of alarm (acknowledgement) - reverse/direct control action - run/hold program selection(level or transition programmable). - program abort - program abort Input type: contact closure (voltage free) Active contact status: close or open programmable
Additional inputs (optional)	For the MKP only 4 + 4 logic inputs are available. Function: Each additional logic input can be programmed as: - run/hold program selection (level or transition programmable) - program selection - program abort Input type: contact closure (voltage free). Active contact status: close or open programmable

MKP and PKP programmers





Wait and guaranteed soak functions

Up to 10 wait bands (each band is formed of the above and the below values) are available to correctly carry out ramps and soaks. Each segment may have different wait bands.

Wait function

If the process variable is outside the programmed wait band, the ramp in progress will be stopped; it will be restarted when the process variable will be returned inside the wait band.

Guaranteed soak function

This function assures that, during a soak, the material is maintained at the temperature set for the entire programmed time. If the process variable is outside the programmed wait band, the soak time count will be stopped, it will restart when the process variable will be returned inside the wait band.

MKC and PKC controllers

CONTROLLERS SPECIFICATIONS

Set points	These instruments are supplied with remote set point (RSP). The transfer from one set point t different programmable rates of	th 4 local set points (selectable by external contact) and an input for the to another may be done by a step transfer or by a ramp with two f rise (ramp up and ramp down)			
	Set point limiters:	set point low limit an	d set point high	limit programma	ble.
	Rate of change for set point variations:	from 1 to 200 digits	per minute or ex	kcluded.	
	Digital filter:	it is possible to apply by the remote set po The time constant of th	y a first order di bint input (RSP) is filter may be pro	gital filter on the ogrammed within (measured value) and 8 s.
Remote set point input (optional)	The remote set point input may be p value will be algebraically added to point).	hay be programmed as trim function also (in this case, the remote set point lided to the selected set point value, the result will be used as operative set			
	Type:	e: not isolated.			
	Scaling:	Scaling: programmable from -1999 to 9999, the decimal figure will be autor cally positioned as for main input. ling time: 500 ms. Accuracy: ± 0.2% f.s.v. ± 1dioit @ 25 °C and nominal power supply.			
	Sampling time: Accuracy:				
	Temperature drift:	300 ppm/°C.			
	STANDARD RANGES TABLE	Ingr	out	Imped	lance
		0 - 20	mA	5	Ω
		4 - 20	mA	5	Ω
		0 - 5	V	> 200	kΩ
		1 - 5	V	> 200	kΩ
		0 - 10	V	> 400	kΩ
		2 - 10	V	> 400	kΩ

Events

All the digital outputs can be programmed as events.

- It is possible to set an event choosing among the following types:
- Error condition on the main input (overrange, underrange, open or short circuit).
- Error condition on the remote set point input (RSP).
- Error condition on both measuring inputs.
- Auto/Manual mode annunciator.
- Local/remote set point annunciator.



MKC and PKC controllers

Logic inputs (optional)	Function: Input type: Active contact status:	these instruments may be supplied with 3 logic inputs, each one can be programmed as: - Set point selection (SP-SP2). - Set point selection (SP3-SP4). - Local/remote set point selection. - Auto/manual mode selection. - Output limiter activation. - Data Hold of the measured value. - Manual reset of alarms (acknowledgement) - Direct/reverse control action. contact closure (voltage free). close or open programmable.
HOLD function	By an external contact it is possible	to stop the input sampling keeping the last measured value frozen.
Three logic inputs, singularly programmable as: - Set point selection (SP-SP2). - Set point selection (SP3-SP4). - Local/remote set point selection. - Auto/manual mode selection. - Output limiter activation. - Data hold of the measured value. - Manual reset of alarms (acknowledgement). - Reverse/direct control action.	Two in program	dependent analog outputs mmable as: - Control output. - Analog retransmission of the measured value - Analog retransmission of the set point value.
Output Programmable output level limiter Start up Programmable time duration of the output level limiting	Programmable output maximum rate of change Time	Soft Start function This function allows to gradually pre-heat the controlled process in order to increase the heater life and to avoid thermal shock. In order to use this function, it is necessary to program the level of power output to be used during pre-heating and its time duration. The alarm masking function assures that no false indication will occur during pre-heating. With these instruments is also possible to set the output power maximum rate of change in order to avoid thermal shock during normal operation.
Set point Two indeper programma (ramp up an for set point	ident ble ramps id ramp down) change Time	Two independent ramps (ramp up and ramp down) for set point changes These products allow to set a ramp for increasing a set point and a ramp for decreasing set point. This solution is essential where it is necessary to produce a gradual set point variation. Moreover, a process may need an heating speed different from cooling.

OFFSET on the measured value

These instruments offer the possibility to set a constant offset applied to the measured value in order to re-align the measured value with the real value of the process.

Ex. In many cases it is quite difficult to place the sensor in an ideal position.

The incorrect positioning of the sensor may produce a measured value that is not a true representation of the process value.

Adjusted curve

Real curve

Second set point change

First set point change

Programmable constant offset

Readout

HOW TO ORDER THE MKC - PKC



HOW TO ORDER THE MKP - PKP

MODEL: MKP = 1 PKP = 1	/4 DIN /8 DIN				
• • • • •	INPUT 1 = M 6 = M 0	C: ain + Au: ain + Au: FD (or F OUT 1 a 11 = Tw 44 = Tw 61 = Or 66 = Tw	x-in. + Logic x-in. + Logic eedback) and OUT 2: o relay outpu o TRIAC out ne SSR + on o SSR outpu	inputs inputs + uts puts e relay output its	
	•	• • • • • • • • • •	OUT 3 and 1 = Two re 2 = Two re interform 0 = 5 = 7 =	dour 4: lay outputs lay outputs ockable by jumper T 5 and OUT 6: Not provided Two mA outputs One mA output (Out 5)	
• • • • • • •	•			OPTIONS: 0 = Not provided 1 = Aux.PWS 2 = RS485 + Aux.PW 4 = Clock calendar + 5 = Clock calendar + 6* = RS485 + Aux.PW 8* = Clock calendar + 5 Digital outputs 9* = Clock calendar + 10 Digital outputs	* <i>MKP only</i> RS485 + Aux.PWS Aux.PWS VS + 4 Logic inputs + 5 Digital outputs VS + 8 Logic inputs + 10 Digital outputs RS485 +Aux.PWS + 4 Logic inputs + RS485 +Aux.PWS + 8 Logic inputs +
		• • • •		POWER SUPPL 3 = 100/240V A 5 = 24V AC/DC	Y: C 0

Optional ACCESSORY

CURRENT TRANSFORMER



- 20 ->



MK DIMENSION, PANEL CUT OUT AND CONNECTION DIAGRAM

(MKP ONLY)

PK DIMENSION, PANEL CUT OUT AND CONNECTION DIAGRAM



REAR PROTECTION

Particular care has been dedicated to the safety rear cover design. The used system assures an easy access to the terminals and it reports a clear description of the connection diagrams without to permit the protection removing.

